

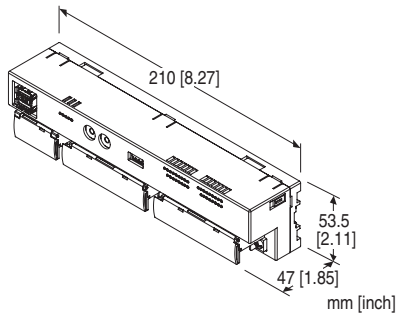
## Remote I/O R7K4F Series

### MECHATROLINK I/O MODULE

(NPN/PNP discrete input, 32 points, screw terminal block, MECHATROLINK-I/-II use)

#### Functions & Features

- 32 points NPN/PNP discrete input module for MECHATROLINK-I/-II



### MODEL: R7K4FML-6-DA32-R[1]

#### ORDERING INFORMATION

- Code number: R7K4FML-6-DA32-R[1]
- Specify a code from below for [1].  
(e.g. R7K4FML-6-DA32-R/Q)
- Specify the specification for option code /Q  
(e.g. /C01)

#### TERMINAL BLOCK

- 6: Screw terminal block for power supply  
Connector for MECHATROLINK-I/-II  
Screw terminal block for I/O

#### I/O TYPE

DA32: NPN/PNP discrete input, 32 points

#### POWER INPUT

##### DC power

R: 24 V DC

(Operational voltage range:  $\pm 10\%$ ; ripple 10 %p-p max.)

#### [1] OPTIONS

blank: none

/Q: With options (specify the specification)

#### SPECIFICATIONS OF OPTION: Q

COATING (For the detail, refer to M-System's web site.)

/C01: Silicone coating

/C02: Polyurethane coating

/C03: Rubber coating

#### GENERAL SPECIFICATIONS

##### Connection

MECHATROLINK: MECHATROLINK-I/-II connector

Power input, input: M3 separable screw terminal (torque 0.5 N·m)

Solderless terminal: Refer to the drawing at the end of the section.

Recommended manufacturer: Japan Solderless Terminal MFG.Co.Ltd, Nichifu Co.,Ltd

Applicable wire size: 0.25 to 1.65 mm<sup>2</sup> (AWG 22 to 16)

Screw terminal: Nickel-plated steel

Housing material: Flame-resistant resin (gray)

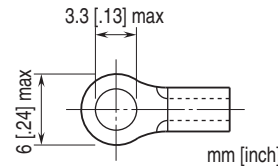
Isolation: Input to MECHATROLINK or FE to power

Status indicator LED: PWR, ERR, SD, RD

(Refer to the instruction manual for details)

Discrete input status indicator LED: Green LED turns on with input ON

##### Recommended solderless terminal



#### MECHATROLINK COMMUNICATION

MECHATROLINK mode: Set with DIP switches

(MECHATROLINK-I or -II, data length; Factory setting:

MECHATROLINK-II; data length (32 byte)

(Refer to the instruction manual)

Station address: 60H - 7FH

(Function selected with Rotary SW. Factory setting: 61H).

(Refer to the instruction manual)

##### MECHATROLINK-I

Baud rate: 4 Mbps

Transmission distance: 50 m max.

Distance between stations: 30 cm min.

Transmission media: MECHATROLINK cable (Model JEPMC-W6003-x-E, Yaskawa Controls Co., Ltd.)

Max. number of slaves: 15

(The maximum number of slaves might change depending on the master unit. Refer to the manual of the master unit)

Transmission cycle: 2 msec. (fixed)

Data length: 17 byte

## ■ MECHATROLINK-II

**Baud rate:** 10 Mbps

**Transmission distance:** 50 m max.

**Distance between stations:** 50 cm min.

**Transmission media:** MECHATROLINK cable (Model JEPMC-W6003-x-E, Yaskawa Controls Co., Ltd.)

**Max. number of slaves:** 30

(The maximum number of slaves might change depending on the master unit. Refer to the manual of the master unit)

**Transmission cycle:** 0.25 msec., 0.5 msec., 1 msec., 1.5 msec., 2 msec., 4 msec., 8 msec.

**Data length:** 17 bytes / 32 bytes selectable (Must choose identical data size for all stations on one network)

## INPUT SPECIFICATIONS

**Common:** Positive or negative common (NPN/PNP) per 32 points

**Maximum inputs applicable at once:** No limit (at 24 V DC)

**Rated input voltage:** 24 V DC  $\pm 10\%$ ; ripple 5 %p-p max.

**ON voltage / current:**  $\geq 15$  V DC (input - COM) /  $\geq 3.5$  mA

**OFF voltage / current:**  $\leq 5$  V DC (input - COM) /  $\leq 1$  mA

**Input current:**  $\leq 5.5$  mA per point at 24 V DC

**Input resistance:** Approx. 4.4 k $\Omega$

**ON delay:**  $\leq 0.5$  msec.

**OFF delay:**  $\leq 1.0$  msec.

## INSTALLATION

**Current consumption**

•DC: Approx. 55 mA

**Operating temperature:** 0 to 55°C (32 to 131°F)

**Storage temperature:** -20 to +65°C (-4 to +149°F)

**Operating humidity:** 30 to 90 %RH (non-condensing)

**Atmosphere:** No corrosive gas or heavy dust

**Mounting:** Surface or DIN rail (35 mm rail)

**Weight:** 330 g (0.73 lb)

## PERFORMANCE

**Insulation resistance:**  $\geq 100$  M $\Omega$  with 500 V DC

**Dielectric strength:** 1500 V AC @ 1 minute (input to power)

500 V AC @ 1 minute (MECHATROLINK or FE to input or power)

## STANDARDS & APPROVALS

**EU conformity:**

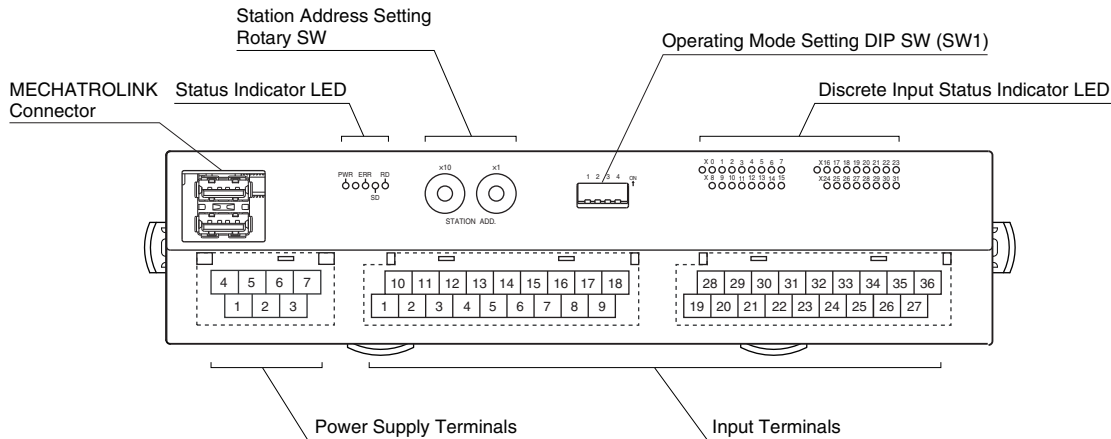
EMC Directive

EMI EN 61000-6-4

EMS EN 61000-6-2

RoHS Directive

## EXTERNAL VIEW



## TERMINAL ASSIGNMENTS

### INPUT TERMINAL ASSIGNMENT

10	11	12	13	14	15	16	17	18
COM	X1	X3	X5	X7	X9	X11	X13	X15
1	2	3	4	5	6	7	8	9
COM	X0	X2	X4	X6	X8	X10	X12	X14

28	29	30	31	32	33	34	35	36
COM	X17	X19	X21	X23	X25	X27	X29	X31
19	20	21	22	23	24	25	26	27
COM	X16	X18	X20	X22	X24	X26	X28	X30

NO.	ID	FUNCTION	NO.	ID	FUNCTION
1	COM	Common	10	COM	Common
2	X0	Input 0	11	X1	Input 1
3	X2	Input 2	12	X3	Input 3
4	X4	Input 4	13	X5	Input 5
5	X6	Input 6	14	X7	Input 7
6	X8	Input 8	15	X9	Input 9
7	X10	Input 10	16	X11	Input 11
8	X12	Input 12	17	X13	Input 13
9	X14	Input 14	18	X15	Input 15

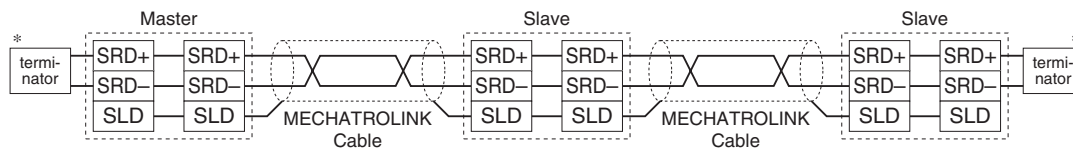
NO.	ID	FUNCTION	NO.	ID	FUNCTION
19	COM	Common	28	COM	Common
20	X16	Input 16	29	X17	Input 17
21	X18	Input 18	30	X19	Input 19
22	X20	Input 20	31	X21	Input 21
23	X22	Input 22	32	X23	Input 23
24	X24	Input 24	33	X25	Input 25
25	X26	Input 26	34	X27	Input 27
26	X28	Input 28	35	X29	Input 29
27	X30	Input 30	36	X31	Input 31

### POWER SUPPLY TERMINAL ASSIGNMENT

4	5	6	7
NC	NC	+24V	0V
1	2	3	
NC	NC	FE	

- 1. NC -
- 2. NC -
- 3. FE Functional earth
- 4. NC -
- 5. NC -
- 6. +24V Power supply (24V DC)
- 7. 0V Power supply (0V)

### MECHATROLINK CONNECTION



\* Terminator

Be sure to connect the terminating resistors to the unit at both ends of transmission line.  
Use the terminating resistor dedicated for MECHATROLINK: Model JEPMC-W6022, Yaskawa Controls Co., Ltd.  
Certain types of Master units may have incorporated terminating resistors. Consult the instruction manual of the Master unit.

## MECHATROLINK RELATED COMMANDS

R7K4FML (Simple I/O) communicates with I/O service with no processor, therefore it uses a connectionless communication protocol. There is no application layer either; the R7K4FML interchanges I/O data via data link layer.

### ■ MECHATROLINK DATA LINK LAYER COMMAND DESCRIPTIONS

The following tables explain the two Commands supported by the R7K4FML.

#### • MDS Command (04H) Data Format

BYTE	COMMAND	RESPONSE	REMARKS
0	MDS (04H)	S(0) (90H)	Message Data Search (MDS) Command: Read the ID from slave station(s) S(0): Response to MDS
1	0	ID	
2	0		
3	0		
4	0	0	All 0
5	0	0	
6	0	0	
7	0	0	
8	0	0	
9	0	0	
10	0	0	
11	0	0	
12	0	0	
13	0	0	
14	0	0	
15	0	0	
16	0	0	
17	0	0	Byte 17 through 31 are always 0 in the 32-byte mode. These bytes are unavailable for MECHATROLINK-I and MECHATROLINK-II in the 17-byte mode.
:	:	:	
31	0	0	

#### • CDRW Command (03H) Data Format

BYTE	COMMAND	RESPONSE	REMARKS
0	CDRW (03H)	ACK (01H)	Cyclic Data Read/Write (CDRW) Command: Link transmission Acknowledge (ACK): Positive response to CDRW
1	Out Data: Lowest	In Data: Lowest	Order of data: Little Endian
2			
3			
4			
5			
6			
7			
8			
9			
10			
11			
12			
13			
14			
15			
16	Out Data: Highest	In Data: Highest	
17	(Out Data: Highest)	(In Data: Highest)	Byte 17 through 31 are unavailable for MECHATROLINK-I and MECHATROLINK-II in the 17-byte mode. (Only available for MECHATROLINK-II in the 32-byte mode)
:			
31			

## I/O DATA DESCRIPTIONS

### ■ DISCRETE INPUT

In 0 to 31:                      0: OFF, 1: ON

#### • 17-BYTE MODE

32 points input, In Data

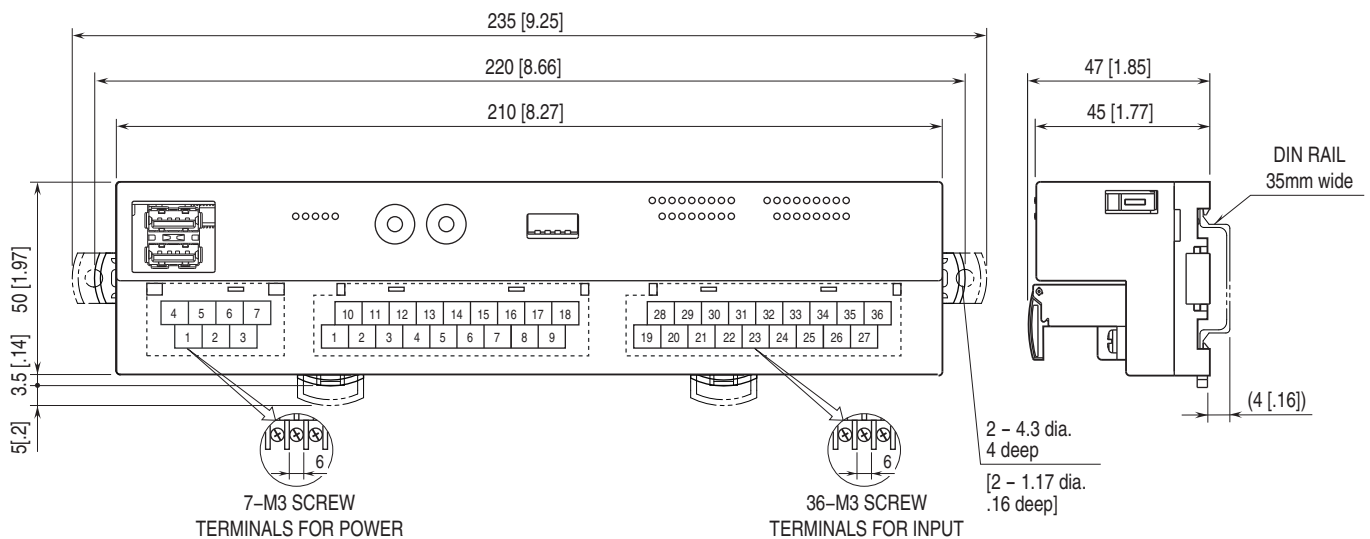
Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
1	In7	In6	In5	In4	In3	In2	In1	In0
2	In15	In14	In13	In12	In11	In10	In9	In8
3	In23	In22	In21	In20	In19	In18	In17	In16
4	In31	In30	In29	In28	In27	In26	In25	In24
5	0	0	0	0	0	0	0	0
⋮	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0
13	0	0	0	0	0	0	0	0
14	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0

#### • 32-BYTE MODE

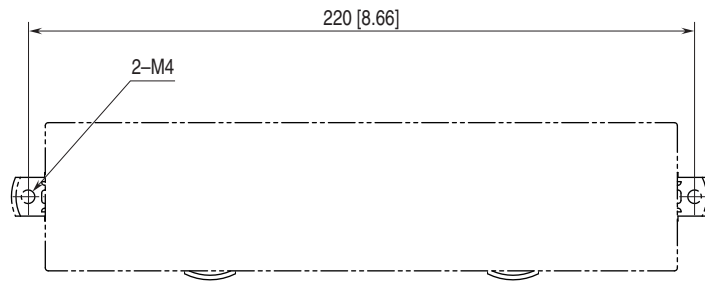
32 points input, In Data

Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
1	In7	In6	In5	In4	In3	In2	In1	In0
2	In15	In14	In13	In12	In11	In10	In9	In8
3	In23	In22	In21	In20	In19	In18	In17	In16
4	In31	In30	In29	In28	In27	In26	In25	In24
5	0	0	0	0	0	0	0	0
⋮	0	0	0	0	0	0	0	0
28	0	0	0	0	0	0	0	0
29	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
31	0	0	0	0	0	0	0	0
32	0	0	0	0	0	0	0	0

## EXTERNAL DIMENSIONS & TERMINAL ASSIGNMENTS unit: mm [inch]



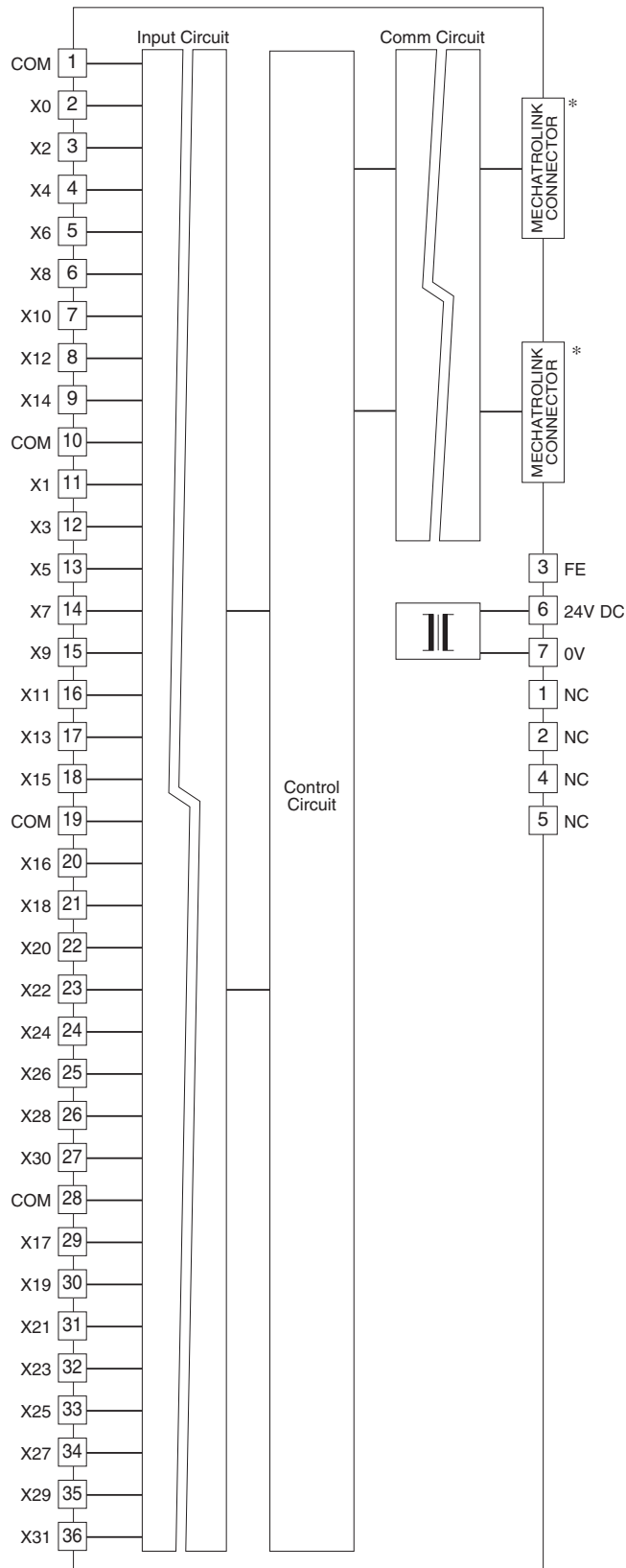
**MOUNTING REQUIREMENTS** unit: mm [inch]



## SCHEMATIC CIRCUITRY & CONNECTION DIAGRAM

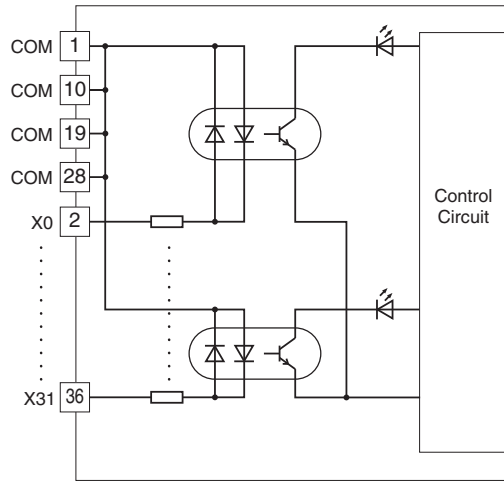
Note: In order to improve EMC performance, bond the FE terminal to ground.

Caution: FE terminal is NOT a protective conductor terminal.



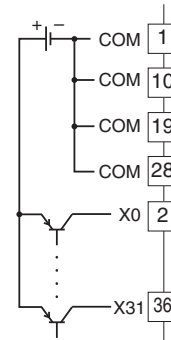
\*MECHATROLINK connectors are internally connected.  
The network cable can be connected to either one.

### Input Circuit

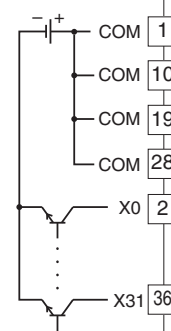


### Input Connection Examples

#### PNP Connection



#### NPN Connection





Specifications are subject to change without notice.