

**BEFORE USE ....**

Thank you for choosing M-System. Before use, please check contents of the package you received as outlined below.

If you have any problems or questions with the product, please contact M-System's Sales Office or representatives.

**■ PACKAGE INCLUDES:**

Discrete input module.....(1)  
DIN rail mounter slider.....(2)

**■ MODEL NO.**

Confirm Model No. marking on the product to be exactly what you ordered.

**■ INSTRUCTION MANUAL**

This manual describes necessary points of caution when you use this product, including installation, connection and basic maintenance procedures.

**POINTS OF CAUTION****■ CONFORMITY WITH EU DIRECTIVES**

- The equipment must be mounted inside the instrument panel of a metal enclosure.
- The actual installation environments such as panel configurations, connected devices, connected wires, may affect the protection level of this unit when it is integrated in a panel system. The user may have to review the CE requirements in regard to the whole system and employ additional protective measures to ensure the CE conformity.

**■ POWER INPUT RATING & OPERATIONAL RANGE**

- Locate the power input rating marked on the product and confirm its operational range as indicated below:  
24V DC rating: 24V  $\pm$ 10%, approx. 75mA

**■ GENERAL PRECAUTIONS**

- Before you remove the unit or mount it, turn off the power supply and input signal for safety.
- Before you remove the terminal block or mount it, turn off the power supply and input signal for safety.

**■ ENVIRONMENT**

- Indoor use.
- When heavy dust or metal particles are present in the air, install the unit inside proper housing with sufficient ventilation.
- Do not install the unit where it is subjected to continuous vibration. Do not subject the unit to physical impact.
- Environmental temperature must be within -10 to 55°C (14 to 131°F) with relative humidity within 30 to 90% RH in order to ensure adequate life span and operation.

**■ WIRING**

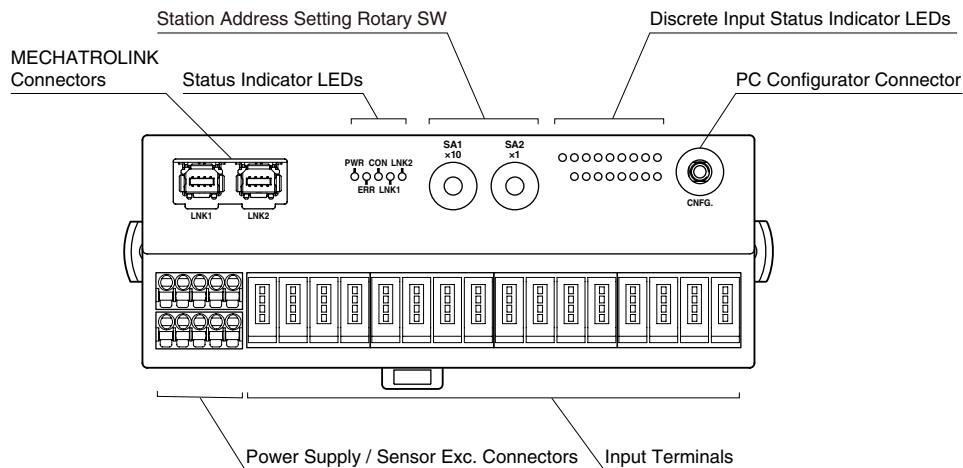
- Do not install cables close to noise sources (relay drive cable, high frequency line, etc.).
- Do not bind these cables together with those in which noises are present. Do not install them in the same duct.
- Be sure to close the terminal cover for safety.

**■ AND ....**

- The unit is designed to function as soon as power is supplied, however, a warm up for 10 minutes is required for satisfying complete performance described in the data sheet.

## COMPONENT IDENTIFICATION

### FRONT VIEW



### STATUS INDICATOR LED

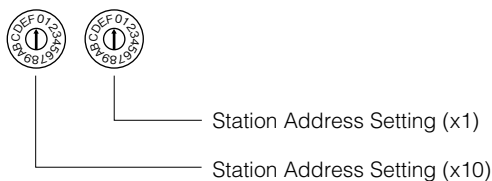
ID	COLOR	FUNCTION
PWR	Green	Turns on when the internal power is supplied normally.
ERR	Red	Turns on when MECHATROLINK-III communication error.
CON	Green	Turns on when MECHATROLINK-III connection is established.
LNK1	Green	Turns on when MECHATROLINK-III LNK1 is established.
LNK2	Green	Turns on when MECHATROLINK-III LNK2 is established.

### STATION ADDRESS

Station Address is selected between 03H and EFH in hexadecimal.

The SA1 switch determines the MSD, while the SA2 switch does the LSD of the address.

(Factory setting: 03H)



### PC CONFIGURATOR JACK

The PC Configurator is used to set the following parameters for each channel.

- Read rate setting (Choose among 1 msec., 5 msec., 10 msec.(\*), 20 msec., 50 msec., 70 msec., 100 msec., 200 msec.)

For more information about the programming using the R7CFG, please refer to the R7CFG Users Manual.

(\*) Factory setting

### DISCRETE INPUT STATUS INDICATOR LED

Discrete input module displays the status of each input with an LED (green).

Contact ON : LED ON

Contact OFF : LED OFF

### POWER SUPPLY TERMINAL ASSIGNMENTS

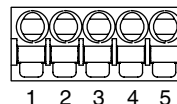
Cable connector: FMC1,5/5-ST-3,5 (Phoenix Contact)

(The cable connector is included in the package.)

Applicable wire size: 0.2 to 1.5 mm<sup>2</sup>  
stripped length: 10 mm

Recommended solderless terminal

- A10,25-10YE 0.25 mm<sup>2</sup> (Phoenix Contact)
- A10,34-10TQ 0.34 mm<sup>2</sup> (Phoenix Contact)
- A10,5-10WH 0.5 mm<sup>2</sup> (Phoenix Contact)
- A10,75-10GY 0.75 mm<sup>2</sup> (Phoenix Contact)
- A1-10 1.0 mm<sup>2</sup> (Phoenix Contact)
- A1,5-10 1.5 mm<sup>2</sup> (Phoenix Contact)



- |               |                   |
|---------------|-------------------|
| 1. PWR +      | Power Supply      |
| 2. PWR -      | Power Supply      |
| 3. FE         | Functional earth  |
| 4. SNSR.EXC + | Sensor excitation |
| 5. SNSR.EXC - | Sensor excitation |

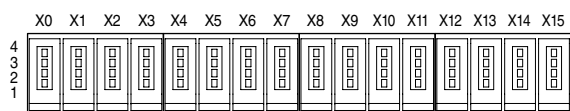
Note: The numbers marked on the connector have no relationship to the pin number of the unit.

Wire according to the instruction manual of the unit.

## INPUT TERMINAL ASSIGNMENTS

Recommended cable connector: 37104-( )-000FL (3M Company)

(The cable connector is not included in the package. Specify wire size instead of ( ); refer to the specifications of the product.)



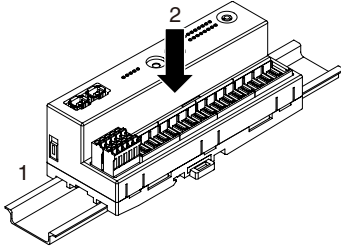
PIN No.	ID	FUNCTION	PIN No.	ID	FUNCTION
X0	1	+24V	X8	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X0		4	X8
X1	1	+24V	X9	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X1		4	X9
X2	1	+24V	X10	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X2		4	X10
X3	1	+24V	X11	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X3		4	X11
X4	1	+24V	X12	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X4		4	X12
X5	1	+24V	X13	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X5		4	X13
X6	1	+24V	X14	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X6		4	X14
X7	1	+24V	X15	1	+24V
	2	NC		2	NC
	3	GND		3	GND
	4	X7		4	X15

## MOUNTING INSTRUCTIONS

### ■ DIN RAIL MOUNTING (PARALLEL)

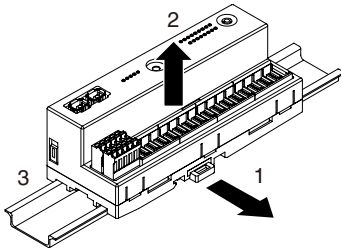
#### • Mounting

- 1) Set the upper hook at the rear side of the unit on the DIN rail.
- 2) Push the lower part in.



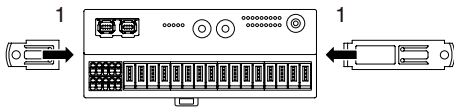
#### • Dismounting

- 1) Push down the DIN rail mouter slider with the tip of a flat-blade screwdriver.
- 2) Pull the lower part of the unit.
- 3) Remove the upper hook of the unit from the DIN rail.

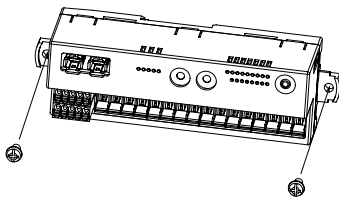


### ■ SURFACE MOUNTING

- 1) Insert the two DIN rail mouter sliders along the rail on the back of the unit until it clicks once, as shown below.



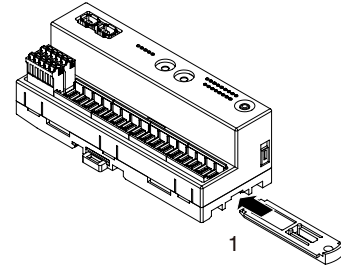
- 2) Mount the unit with M4 screws referring to the External Dimensions. (Torque: 1.4 N·m)



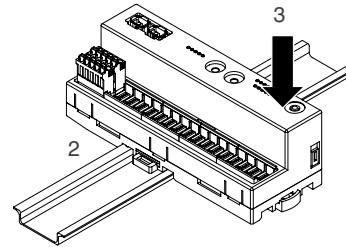
### ■ DIN RAIL MOUNTING (RIGHT ANGLE)

#### • Mounting

- 1) Insert the longer DIN rail mouter slider along the rail on the back of the unit until it clicks twice, as shown below.

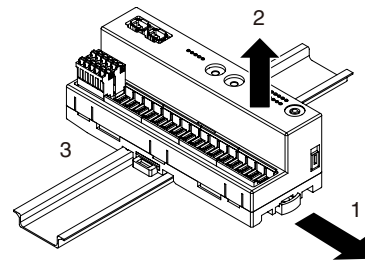


- 2) Set the upper hook at the rear side of the unit on the DIN rail.
- 3) Push the lower part in.



#### • Dismounting

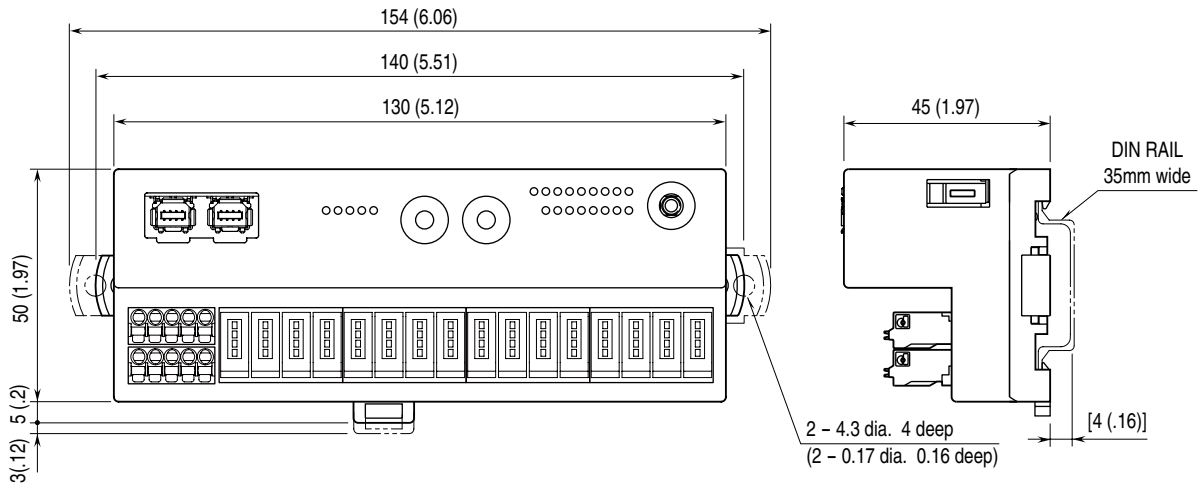
- 1) Push down the DIN rail mouter slider with the tip of a flat-blade screwdriver.
- 2) Pull the lower part of the unit.
- 3) Remove the upper hook of the unit from the DIN rail.



# TERMINAL CONNECTIONS

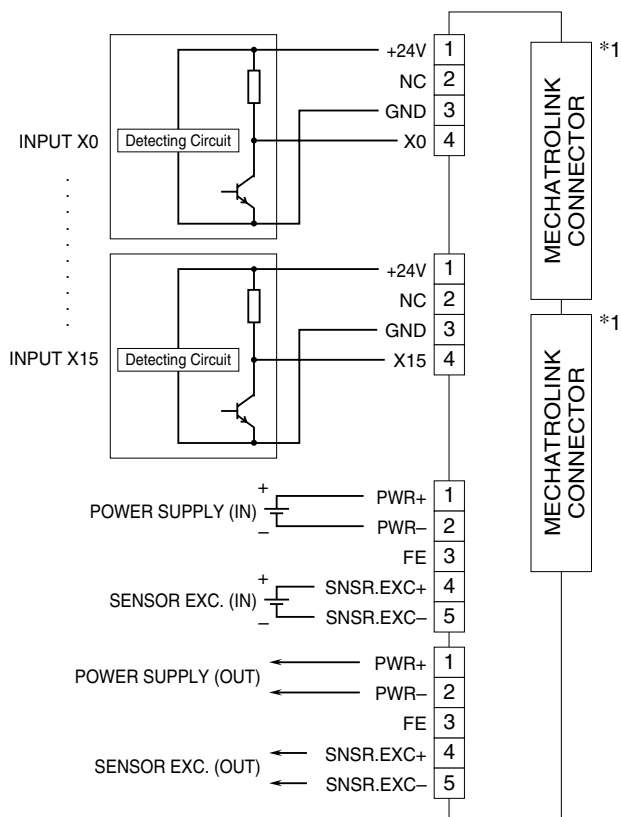
Connect the unit as in the diagram below.

## EXTERNAL DIMENSIONS unit: mm (inch)



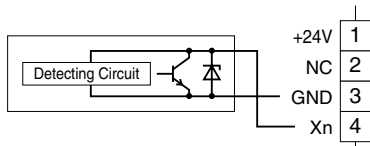
## CONNECTION DIAGRAM

Note: In order to improve EMC performance, bond the FE terminal to ground.  
 Caution: FE terminal is NOT a protective conductor terminal.

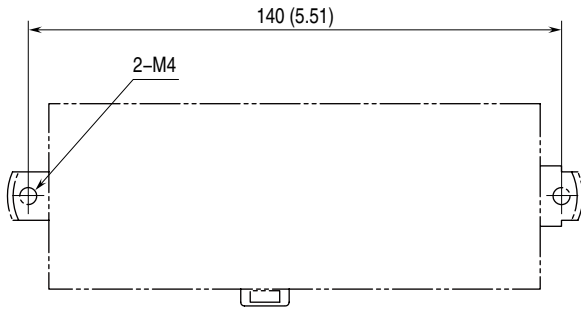


\*1. The network cable can be connected to either one.

## 2-Wire Sensor



## MOUNTING REQUIREMENTS unit: mm (inch)



## MECHATROLINK-III COMMUNICATION

**Transmission cycle:** 125  $\mu$ sec., 250  $\mu$ sec., 500  $\mu$ sec., 1 – 64 msec. (with 1 msec. increments)

**Communication cycle:** 125  $\mu$ sec. through 64 msec.

**Applicable profile:** Standard I/O profile (cyclic communication)

Event-driven communication acquiring ID profile (event-driven communication)

**Data size:** 16 bytes

**Station address:** 03H through EFH (set with rotary switches)

**Cyclic communication:** Available

**Event-driven communication:** Available

**Slave monitoring:** None

## MECHATROLINK-III COMMAND

Commands available with this unit are as follows.

PROFILE	COMMAND	CODE	FUNCTION
Common command	NOP	00H	No operation command
	ID_RD	03H	Read ID command
	CONFIG	04H	Setup device command
	ALM_RD	05H	Read alarm or warning command
	ALM_CLR	06H	Clear alarm or warning command
	CONNECT	0EH	Establish connection command
	DISCONNECT	0FH	Release Connection command
Standard I/O command	DATA_RWA	20H	Transmit I/O data

### • NOP (00H)

Does nothing except sending back current status

BYTE	COMMAND	RESPONSE	REMARKS
0	NOP (00H)	NOP (00H)	No operation command
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
$\geq 4$	00H	00H	Reserve

#### • ID\_RD (03H)

Reads the product ID.

BYTE	COMMAND	RESPONSE	REMARKS
0	ID_RD (03H)	ID_RD (03H)	Read ID command
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
4	ID_CODE	ID_CODE	Refer to ID_CODE.
5	OFFSET	OFFSET	OFFSET: designates the place to read data.
6	SIZE	SIZE	SIZE: specifies the size of data to read.
7			
≥ 8	00H	ID	Product's ID

#### • CONFIG (04H)

No parameter to set for this unit. Immediately responds with completion.

BYTE	COMMAND	RESPONSE	REMARKS
0	CONFIG (04H)	CONFIG (04H)	Setup device command
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
4	00H	00H	Recalculation of parameters and set up Command parameters other than "0" are not supported.
≥ 5	00H	00H	Reserve

#### • ALM\_RD (05H)

Reads alarm or warning

BYTE	COMMAND	RESPONSE	REMARKS
0	ALM_RD (05H)	ALM_RD (05H)	Read alarm or warning command
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
4	0000H	0000H	Read current alarm or warning. 12 points max. (2 bytes in 8th to 31st byte) Command parameters other than "0" are not available.
5			
6	0000H	0000H	0
7			
≥ 8	00H	00H	0

#### • ALM\_CLR (06H)

Clears alarm or warning

BYTE	COMMAND	RESPONSE	REMARKS
0	ALM_CLR (06H)	ALM_CLR (06H)	Clear alarm or warning command
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
4	0000H	0000H	Clears current alarm or warning. Command parameters other than "0" are not available.
5			
≥ 6	00H	00H	Reserve

### • CONNECT (0EH)

Starts communication with master station.

BYTE	COMMAND	RESPONSE	REMARKS
0	CONNECT (0EH)	CONNECT (0EH)	Establish connection command
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
4	30H	30H	MECHATROLINK application layer: 30H
5	00H	00H	Communication mode Asynchronous, single transmission, subcommand disabled
6	COM_TIME	COM_TIME	Communication cycle: Multiple of transmission cycle E.g. Transmission cycle: 0.5 msec., communication cycle: 2 msec. 4 (=2/0.5) is set.
7	30H or 01H	30H or 01H	Profile type 30H: Standard I/O 01H: Event-driven
≥ 8	00H	00H	Reserve

### • DISCONNECT (0FH)

Stops communication with master station.

BYTE	COMMAND	RESPONSE	REMARKS
0	DISCONNECT (0FH)	DISCONNECT (0FH)	Release Connection command
≥ 1	00H	00H	Reserve

### • DATA\_RWA (20H)

Transmits I/O data to master station. Data allocation is as follows.

Data size is 16 bytes.

BYTE	COMMAND	RESPONSE	REMARKS
0	DATA_RWA (20H)	DATA_RWA (20H)	Transmits I/O data.
1	00H	00H	Not used
2	CMD_CTRL	CMD_STAT	Refer to CMD_CTRL/CMD_STAT.
3			
4	CH0 OUT LO	CH0 IN LO	CHx OUT: Output data (Refer to “ Output Data ” under Input / Output Data Details)
5	CH0 OUT HI	CH0 IN HI	
6	CH1 OUT LO	CH1 IN LO	
7	CH1 OUT HI	CH1 IN HI	
8	CH2 OUT LO	CH2 IN LO	
9	CH2 OUT HI	CH2 IN HI	
10	CH3 OUT LO	CH3 IN LO	CHx IN: Input data (Refer to “ Input Data ” under Input /Output Data Details)
11	CH3 OUT HI	CH3 IN HI	
12	00H	00H	Not used
13	00H	00H	Not used
14	00H	00H	Not used
15	00H	00H	Not used

### • Input /Output Data Details

Input Data: Slave stations → master station read back value is configured.

CH0 IN LO	CH0 Data Low order 8 bits	Input data bits 0 – 7 are configured.
CH0 IN HI	CH0 Data High order 8 bits	Input data bits 8 – 15 are configured.
CH1 IN LO	CH1 Data Low order 8 bits	Not used
CH1 IN HI	CH1 Data High order 8 bits	Not used
CH2 IN LO	CH2 Data Low order 8 bits	Not used
CH2 IN HI	CH2 Data High order 8 bits	Not used
CH3 IN LO	CH3 Data Low order 8 bits	Not used
CH3 IN HI	CH3 Data High order 8 bits	Not used

Output Data: Slave stations → master station data is configured.

CH0 OUT LO	CH0 Data Low order 8 bits	Not used
CH0 OUT HI	CH0 Data High order 8 bits	Not used
CH1 OUT LO	CH1 Data Low order 8 bits	Not used
CH1 OUT HI	CH1 Data High order 8 bits	Not used
CH2 OUT LO	CH2 Data Low order 8 bits	Not used
CH2 OUT HI	CH2 Data High order 8 bits	Not used
CH3 OUT LO	CH3 Data Low order 8 bits	Not used
CH3 OUT HI	CH3 Data High order 8 bits	Not used



**CMD\_CTRL**

CMD\_CTRL command area is as follows.

BIT	FUNCTION	REMARKS
0 - 2	Reserve	Not used
3	ALM_CLR	0: Clear alarm/warning disabled 1: Clear alarm/warning triggered
4 - 5	Reserve	Not used
6 - 7	CMD_ID	Not used in the standard I/O profile command
8 - 15	Reserve	Not used

**CMD\_STAT**

CMD\_STAT response area is as follows.

BIT	FUNCTION	REMARKS	
0	D_ALM	Not used	
1	D_WAR	Not used	
2	CMDRDY	1: Command reception enabled 0: Other	
3	ALM_CLR_CMP	1: Completion of execution of ALM_CLR 0: Other ALM_CLR_CMP can be cancelled by setting "0" for CMD_CTRL.ALM_CLR.	
4 - 5	Reserve	Not used	
6 - 7	RCMD_ID	Not used in the standard I/O profile command	
8 - 11	CMD_ALM	Warning	0: Normal, 1: Invalid data
		Alarm	8: Unsupported command received, 9: Invalid data, A: Command execution condition error, B: Subcommand combination error, C: Phase error
12 - 15	COMM_ALM	Warning	0: Normal, 1: FCS error, 2: Command data not received, 3: Synchronous frame not received
		Alarm	8: FCS error, 9: Command data not received, A: Synchronous frame not received, B: Synchronization time interval error, C: WDT error

**ID\_CODE**

ID\_CODE is as follows.

ID_CODE (HEX.)	NAME	SIZE (BYTES)	SUP-PORT	VALUE (HEXADECIMAL)	REMARKS
01	Vendor ID Code	4	Yes	0x00000021	M-SYSTEM CO., LTD.
02	Device Code	4	Yes	0x00000700	R7G4FML3-B-DA16A
03	Device Version	4	Yes	Firmware version	E.g. 1.00 -> 0x0064
04	Device Definition File version	4	Yes	0x00001000	
05	Extended Address Setting	4	Yes	0x00000001	
06	Serial No.	32	Yes	Unit serial number	E.g. AB123456-> 0x32314241 0x36353433 0x00000000 0x00000000 0x00000000 0x00000000 0x00000000 0x00000000
10	Profile Type 1	4	Yes	0x00000030	Standard I/O profile
11	Profile Version 1	4	Yes	0x00000100	
12	Profile Type 2	4	Yes	0x000000FF	Indicates the unit does not support.
13	Profile Version 2	4	Yes	0x00000000	
14	Profile Type 3	4	Yes	0x000000FF	Indicates the unit does not support.
15	Profile Version 3	4	Yes	0x00000000	
16	Min. Transmission Cycle	4	Yes	0x000030D4	125 µsec.
17	Max. Transmission Cycle	4	Yes	0x0061A800	64 msec.
18	Increments of Transmission Cycle	4	Yes	0x00000001	Available to 31.25, 62.5, 125, 250, 500 [µsec.] & 1 – 64 [msec.] (1 msec. increments)
19	Min. Communication Cycle	4	Yes	0x000030D4	125 µsec.
1A	Max. Communication Cycle	4	Yes	0x0061A800	64 msec.
1B	Transmission Bytes	4	Yes	0x00000002	16 Bytes
1C	Transmission Bytes (Current Setting)	4	Yes	0x00000002	16 Bytes
1D	Profile Type (Current Selection)	4	Yes	0x00000001 / 0x00000030	Event-driven communication / Cyclic communication
20	Supported Communication Mode	4	Yes	0x00000003	Event-driven communication / Cyclic communication
21	MAC Address	4	No	–	
30	List of Supported Main Commands	32	Yes	0x0000C079 0x00000001 0x00000000 0x00000000 0x00000000 0x00000000 0x00000000 0x00000000 0x00000000	ALM_CLR, ALM_RD, CONFIG, ID_RD, NOP, DISCONNECT, CONNECT, DATA_RWA
38	List of Supported Sub Commands	32	No	–	
40	List of Common Parameters	32	No	–	
80	Main Device Name	32	Yes	0x34473752 0x334C4D48 0x442D442D 0x41363141 0x00000000 0x00000000 0x00000000 0x00000000	"R7G4FML3-B-DA16A"
90	Sub Device 1 Name	4	No	–	
98	Sub Device 1 Version	32	No	–	
A0	Sub Device 2 Name	4	No	–	
A8	Sub Device 2 Version	32	No	–	
B0	Sub Device 3 Name	4	No	–	
B8	Sub Device 3 Version	32	No	–	

## I/O DATA DESCRIPTION

### ■ DISCRETE INPUT

